

PROGRAMMABLE LOGIC CONTROLLER

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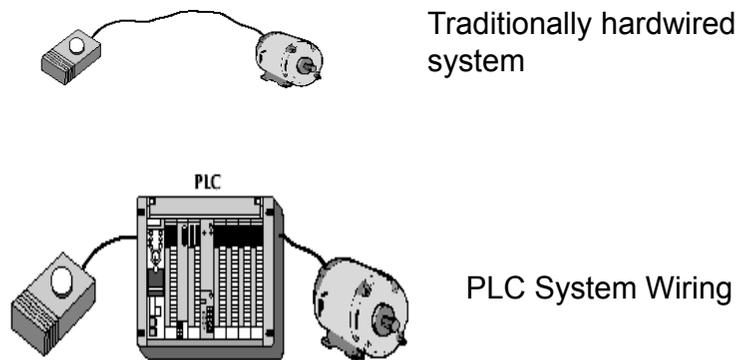
PLC TERMINOLOGY AND APPLICATIONS

Programmable Logic Controller, also called a *PLC* or *programmable controller*, is a computer-type device used to control equipment in an industrial facility.

PLC Applications: Process Control, HVAC Control, Conveyor Systems, Food Processing Machinery, Auto Assembly Lines, etc. (Regulatory Control as well as Sequential Control Systems)

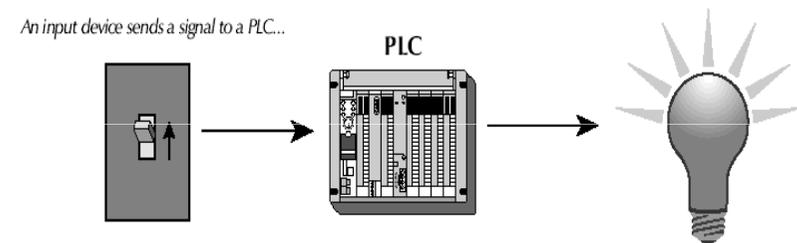
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SYSTEM WIRING COMPARISON



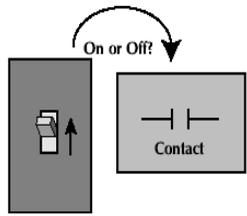
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PLC SYSTEM INPUT/OUTPUT

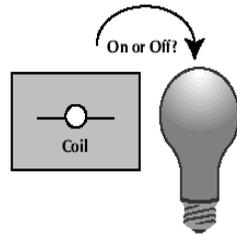


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RELAY AND COIL

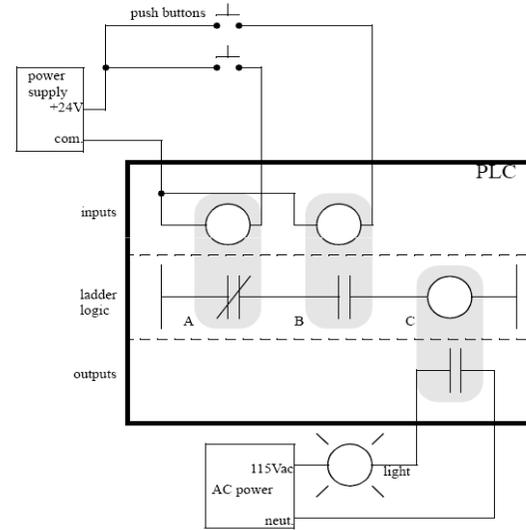


A contact is a computer code that monitors the status of an input...

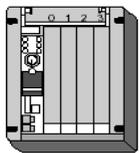


...A coil is a computer code that monitors the status of an output.

PLC SYSTEM WITH RELAYS



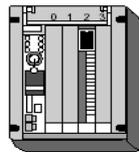
SYSTEM RACK COMPONENTS



A rack is an enclosure with slots...



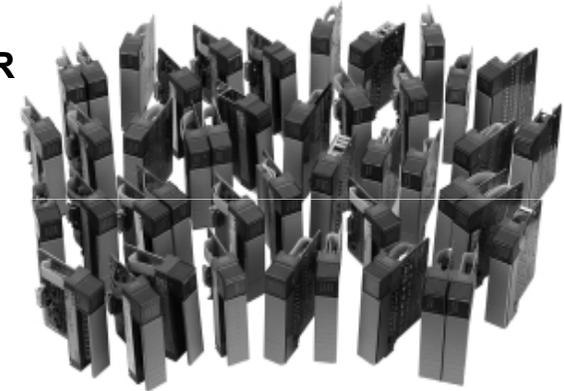
...into which I/O modules...

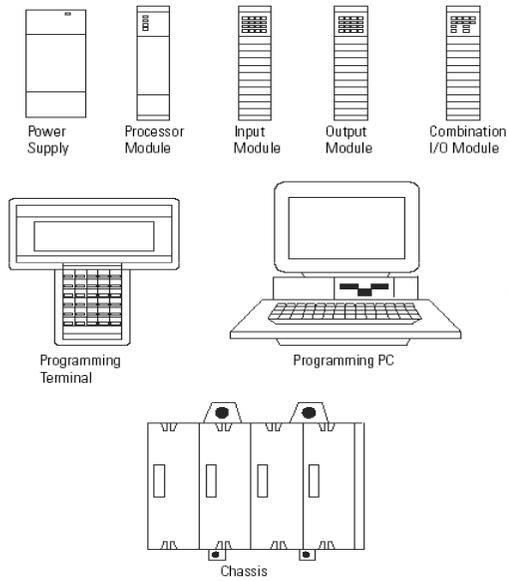


...are installed.

PLC MODULES I/O MODULES

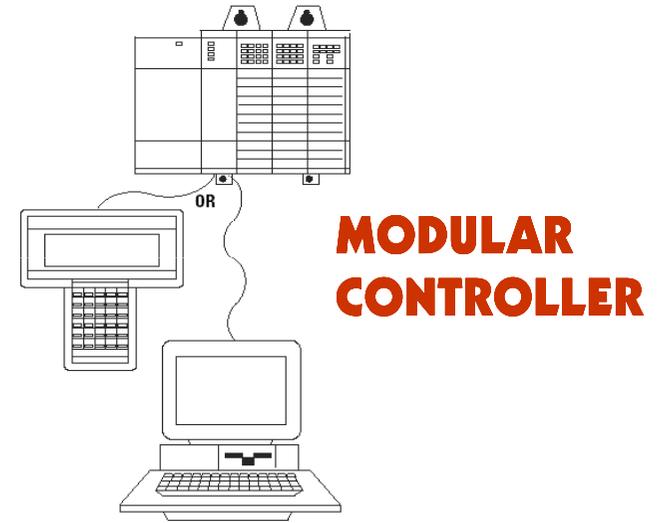
PROCESSOR





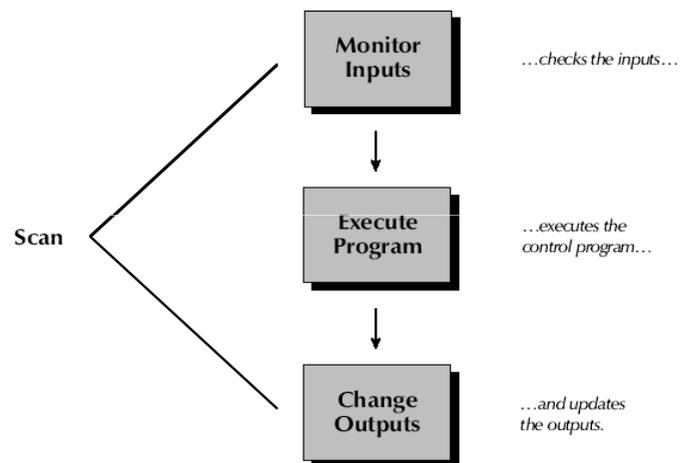
PLC MODULES

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PLC PROGRAM FLOW



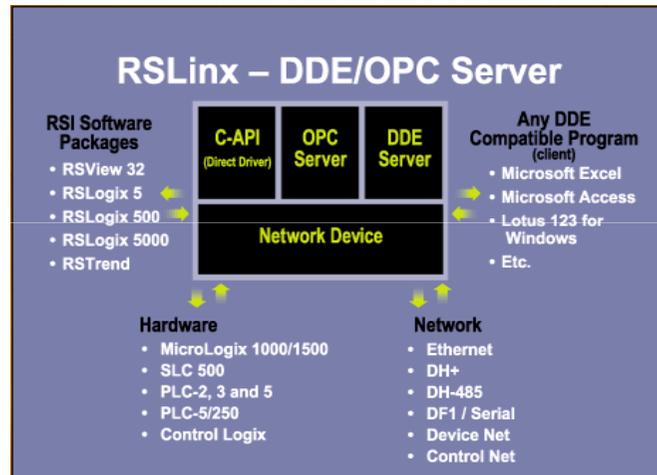
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DIRECT PC-PLC LINK



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PC-PLC LINK SOFTWARE TOOL



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PC-PLC LINK SOFTWARE TOOL



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PLC PROGRAM UP-LOAD



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PLC PROGRAM DOWN-LOAD



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ON-LINE EDITING



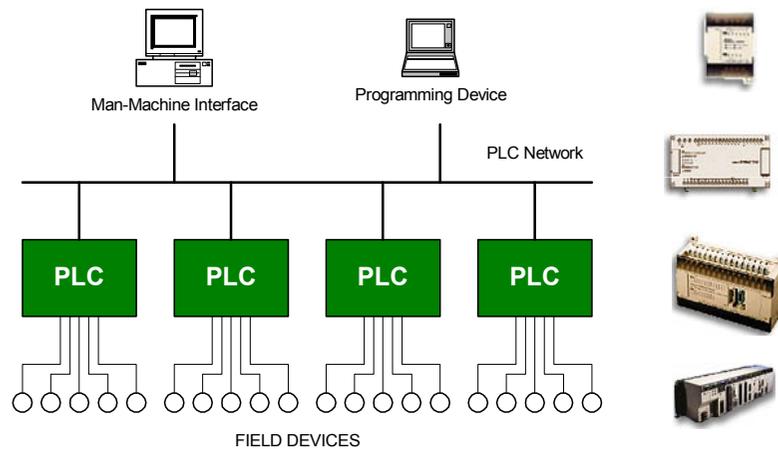
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ON-LINE EDITING FUNCTIONS

- ❖ Inserting Rungs
- ❖ Replacing Rungs
- ❖ Deleting Rungs
- ❖ Documenting Program
- ❖ Modifying Addresses or Instruction Types

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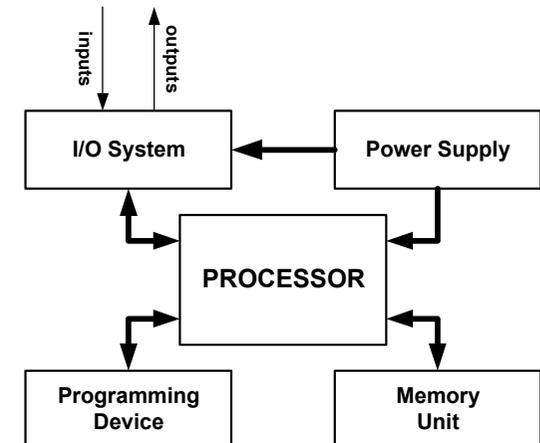
A Picture of PLC System



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Basic Components of PLC

- 4 Processor
- 4 Memory
- 4 I/O Interface
- 4 Programming Device & Languages
- 4 Power Supply



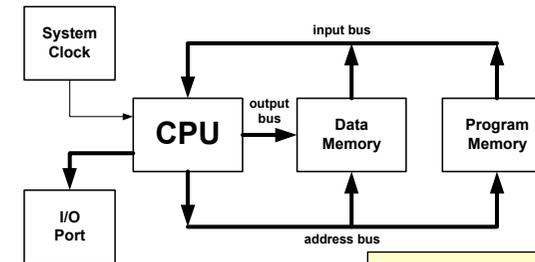
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How does a PLC work ?

- Examine the status of inputs and outputs
- Controls some process or machine through outputs using some control logic
- This control logic is executed periodically by the processor in a predetermined sequential order
- User can change the control logic using a programming language and it is stored in the program memory

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Processor & Memory



- ◆ 80386/80486 microprocessor based
- ◆ Random Access Memory (RAM)
- ◆ Electrically Erasable Programmer Read Only Memory (EEPROM)

Instruction cycle :

- Fetch the next instruction from program memory
- Place it in the instruction register in the CPU
- Increment the program counter by one
- Execute the instruction

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Input/Output Systems

- ◆ Discrete Inputs/Outputs
- ◆ Analog Inputs/Outputs
- ◆ Special Purpose Modules
- ◆ Intelligent Modules
- ◆ Communication Modules

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Discrete Signal Types

- Selector switches
- Temperature switches
- Flow switches
- Level switches
- Valve position switches
- Starter auxiliary contacts
- Pushbuttons
- Motor starter contacts
- Limit switches
- Pressure switches
- Hand switches
- Proximity switches
- Relay contacts
- Photoelectric sensors
- Annunciators
- Alarm lights
- Electric control relays
- Electric fans
- Indicating lights
- Electric valves
- Alarm horns
- Solenoid valves
- Motor starters
- Heater starters

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Discrete Input Modules

◆ AC and DC Discrete Input Module

- Electrical isolation between the field device (power) and the controller (logic)
- Common return line connection
- ACI-XX where XX is voltage (120 and 220 VAC)
- DCI-XX where XX is voltage (12, 24, and 48 VDC)

◆ TTL

- TTL-compatible devices (solid-state controller and sensing instruments)
- external +5 V dc power supply

◆ Isolated Input Module

- Separated return lines
- IACI-XX or IDCI-XX

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Discrete Output Module

◆ AC Output Module

- AC loads (using Triac/ SCR as switch)
- RC snubber protection
- Peak voltage limiter (metal oxide varistor - MOV)
- Fuse protection
- External switching voltage

◆ DC Output Module

- DC loads (using power transistors)
- Fuse protection

◆ TTL Output Module

- TTL-compatible output devices (seven segment LED, IC, and +5 Vdc logic-based devices)
- External +5 Vdc power supply

◆ Isolated AC Output Module

◆ Dry Contact

- Normally open (NO)
- Normally closed (NC)

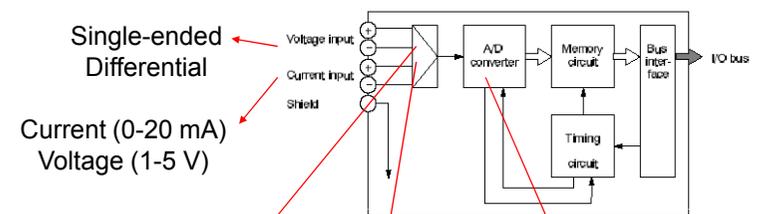
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Analog Devices

- | | |
|----------------------------|------------------------------------|
| ■ Flow transmitters | ■ Electric motor drives |
| ■ Pressure transmitters | ■ Analog meters |
| ■ Temperature transmitters | ■ Chart data recorders |
| ■ Analytical transmitters | ■ Process controllers |
| ■ Position transmitters | ■ Current-to-pneumatic transducers |
| ■ Potentiometers | ■ Electrical-operated valve |
| ■ Level transmitters | ■ Variable speed drives |
| ■ Speed instruments | |

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Analog Input Module

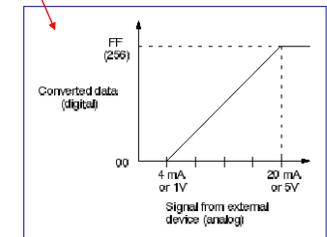


Single-ended
Differential

Current (0-20 mA)
Voltage (1-5 V)

Very high input
impedance to prevent
signal loading

Filtering and
isolation circuits

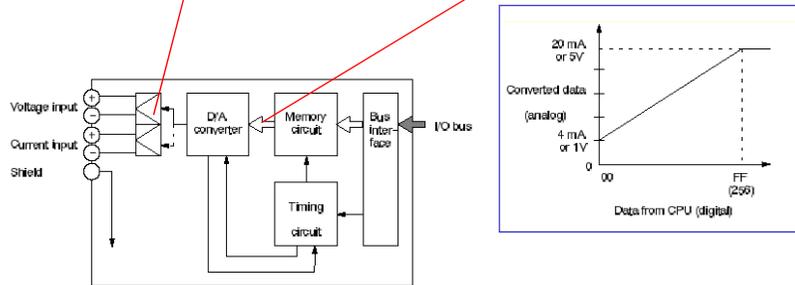


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Analog Output Module

Isolation between the output circuit and the logic circuit is provided through optical couplers

Receive data from the CPU which is translated into a proportional voltage/current to control an analog field device



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Special Purpose Modules

- ◆ **Binary Coded Decimal (BCD) Modules**
 - Provide parallel communication between the processor and input/output devices
- ◆ **Encoder/Counter Input Module**
 - Used for operations that require direct high speed encoder input into a counter
- ◆ **Pulse Counter Input Module**
 - Used to interface with field instruments that generate pulse such as positive displacement (PD) flowmeters and turbine type flowmeters

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Intelligent Module

- ◆ Can perform complete processing functions, independent of the CPU and the control program scan
- ◆ **Thermocouple Input Module**
 - Designed to accept inputs directly from a thermocouple
 - Provides cold junction compensation
- ◆ **Stepping Motor Module**
 - Generates a pulse train that is compatible with stepping motor translators that represent distance, speed, and direction commands
- ◆ **Control Loop Module (PID module)**
 - Used in continuous closed-loop where the proportional-integral-derivative (PID) control algorithm is required

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Communication Module

- ◆ **ASCII**
 - Used to send and receive alphanumeric data between peripheral equipment and the controller
- ◆ **PCMCIA Interface Card**
 - Allows communications between PLC or data highway and notebook PC
- ◆ **Ethernet**
 - Designed to allow a number of PLC and other computer-based devices to communicate over a high speed plant local area network
- ◆ **Fiber Optic Converter**
 - Transform electrical signals and transmit these signals through fiber optic cables
- ◆ **Universal Remote I/O Link**
 - Allows I/O subsystems to be remotely located from the processor (1000 ft to several miles)
- ◆ **Serial Communications Module**
 - Used to communicate between the programmable controller and an intelligent instrument with a serial output
 - RS-232C, RS-422, or RS-485 communication link

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Designing I/O Systems : Electrical

- ◆ **Input voltage rating**
 - Lists the magnitude and type of signal the module will accept
- ◆ **Input current rating**
 - The minimum input current required at the module's rated voltage that the field device must be capable of supplying to operate the input module circuit
- ◆ **Input threshold voltage**
 - The voltage at which the input signal is recognized as being ON/true
- ◆ **Output voltage rating**
 - The magnitude and type of voltage that can be controlled within a stated tolerance
- ◆ **Output current rating**
 - The maximum current that a single output circuit in a module can safely carry under load
- ◆ **Output power rating**
 - The maximum total power that an output module can dissipate with all output energized
- ◆ **Backplane current requirements**
 - Lists the current demand that a particular I/O module internal circuitry places on the rack power supply

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Designing I/O Systems : Mechanical

- ◆ Number of I/O points per module
- ◆ Number of wires
- ◆ Wire size specification
 - Number of conductors
 - Largest wire gage that the I/O terminal points will accept
- ◆ Ambient temperature rating
 - Based on the heat dissipation characteristics of the circuit components inside the I/O module
 - 0 - 60 C typical
- ◆ Humidity rating
 - 5 - 95 % typical relative humidity

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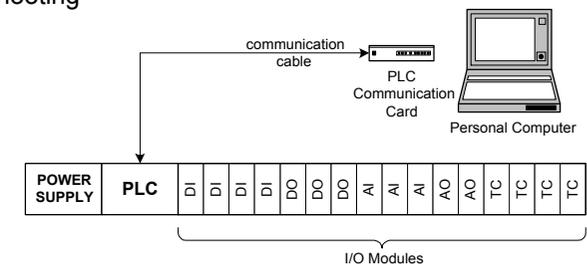
IEC1131-3 Standard Languages

- ◆ **Ladder Diagram (LD)**
 - Uses a standardized set of ladder logic symbols
- ◆ **Sequential Function Charts (SFC)**
 - Blocks connected together like a circuit diagram
- ◆ **Functional Block Diagram (FBD)**
 - A graphical language used to describe sequential operations
- ◆ **Instruction List (IL)**
 - Low level language
- ◆ **Structured Text (ST)**
 - High level structured language designed for automation processes

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Programming Devices

- ◆ Used to enter, store, and monitor the PLC software
- ◆ PC-based system
- ◆ Connected to the PLC only during :
 - programming & testing
 - startup
 - troubleshooting

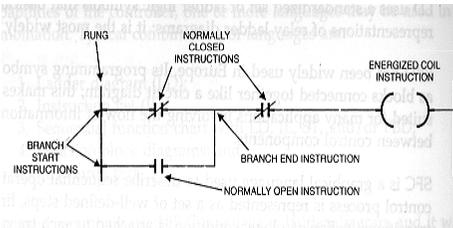


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Ladder Diagram (LD)

- ◆ Representations of relay ladder diagrams
- ◆ The most widely used
- ◆ Composed of six categories of instructions

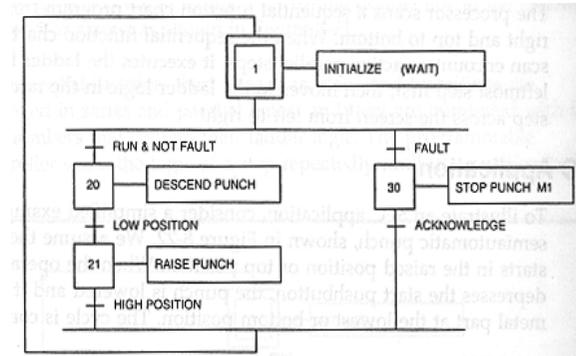
- Relay type
- Timer/counter
- Data manipulation
- Arithmetic
- Data transfer
- Program control



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Sequential Function Charts (SFC)

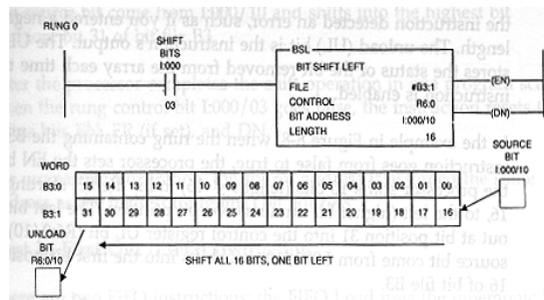
- ◆ Represented as a set of well-defined steps, linked by transitions
- ◆ Actions within the steps are detailed by using the Structured Text language (ST)



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Functional Block Diagram (FBD)

- ◆ Describes a relationship or function between input and output variables
- ◆ Well suited for many applications involving the flow of information or data between control components
- ◆ Allows the programmer to build complex control procedures
- ◆ Extensive function blocks library is provided



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Instruction List (IL)

- ◆ Very effective for small simple applications or for optimizing parts of an application
- ◆ A list of low level instructions
- ◆ Consists of standardized operators
 - Data manipulation
 - Arithmetic
 - Branch instruction

Example :

Start :	LD	IX1	(* load input IX1, start pushbutton *)
	ANDN	MX5	(* AND with NOT of MX5)
	ST	QX2	(* store output QX2 to start motor *)

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Structured Text (ST)

- ◆ Used mainly to implement complex procedures
- ◆ Default language for the description of the actions within steps and conditions attached to the transitions of the SFC

◆ Statement types :

- assignment
- subprogram or function call
- "C" function block call
- Selection (if, then, else, case, etc)
- Iteration (for, while, repeat, etc)
- Control (return, exit, etc)
- Special

```
imax:=max_ite;  
cond:=X12;  
if not(cond(*alarm*))  
then return;  
end_if;  
  
for i:=1 to max_ite do  
if i<>2 then  
SPcall();  
end_if;  
end_for;
```

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PLC System Design

1. Process Description
2. I/O Sizing
3. Memory Sizing
4. Selecting programming language
5. Peripheral requirements
6. System drawing and I/O wiring diagrams
7. System programming

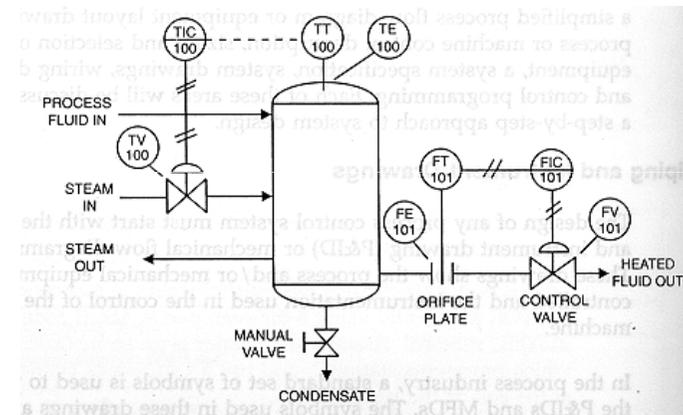
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Process Description

- ◆ States the purpose and the steps of the process/plant operation
- ◆ Process Description is the most important step in the design process
- ◆ Bridge of communications between the user and the designer
 - Piping and Instrument Diagram (P&ID) and Mechanical Flow Diagrams (MFDs)
 - Simplified drawing that shows only the equipment and instrumentation controlled or measured by the PLC is required
 - This drawing will be used to show the status of the process in each step or state to aid in the programming of the system

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Piping & Instrument Diagram (P&ID)



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I/O Sizing (1)

- ◆ Estimate the number of input/output (I/O) required to control the process
 - Obtain the number of device from P&ID diagram
 - Add the number of I/O points from each devices to obtain total I/O points
- ◆ Consider different types of I/O :
 - Discrete AC/DC : Limit switches, push buttons, selector switches, solenoid, etc.
 - TTL : solid state displays and electronic instrumentation
 - Analog : Level transmitter, pressure transmitter, etc.
 - Encoders

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I/O Sizing (2)

- ◆ Select PLC size :
 - **Micro** : up to 32 I/O points
 - **Small** : 32 - 256 I/O points
 - **Medium** : 256 - 1024 I/O points
 - **Large** : > 1024 I/O points
- ◆ Estimate the number of I/O module
 - Classify each type of I/O points (discrete, analog, isolated, TTL, dry contact)
 - Select suitable I/O modules from PLC manual and obtain the number of I/O points per module
 - The number of each I/O module type required = $[Total\ I/O\ points] / [Number\ of\ I/O\ points\ per\ module]$
- ◆ Add spare and future expansions (10-20% spare capacity)

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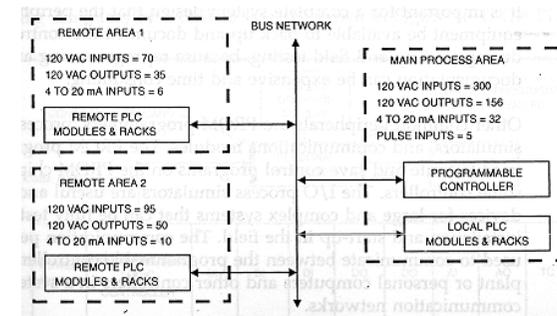
Memory Sizing

- ◆ The amount of memory required depends on :
 - control program complexity
 - the number of I/O points
- ◆ Precise (*almost impossible*) method to determine memory size :
 - Write out the control program
 - Count the number of instructions used
 - Multiply this count by the number of words used per instructions (obtained from PLC programming manual)
 - Add the amounts of memor used by executive programs and the processor overhead
- ◆ **Practical method** :

$Total\ memory = 10 \times [the\ number\ of\ I/O\ points]$

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I/O and Memory Sizing Example

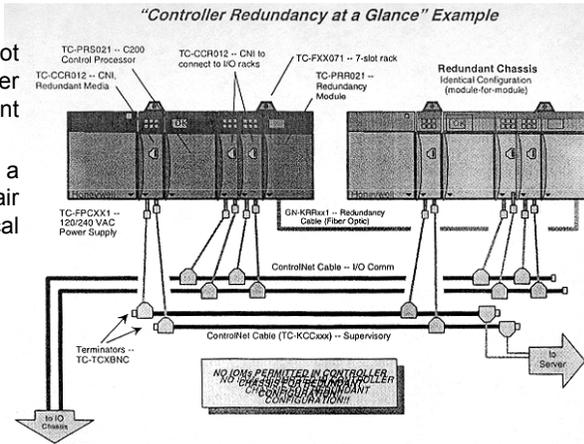


- ◆ I/O Points
 - Remote Area 1 : I/O = 70 + 35 + 6 = 111
 - Remote Area 2 : I/O = 95 + 50 + 10 = 155
 - Main Process Area : I/O = 300 + 156 + 32 + 5 = 493
 - Total I/O points = 759
 - Spare points = 10% x 759 = 76
- ◆ PLC size = Medium-sized (1024 I/O points max.)
- ◆ Memory size = 10 x 759 = 7590 or 8K

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Redundant Configuration

- ◆ I/O modules are not permitted in either chassis of a redundant chassis pair
- ◆ Both chassis of a redundant chassis pair must have identical slot-for-slot configurations



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Selecting Programming Language

- ◆ Most PLCs offer the basic ladder logic instructions plus a combination of the other types of languages
- ◆ Programming language selections is depends on :
 - Complexity of the control system
 - Background knowledge of the control system programmers and operators

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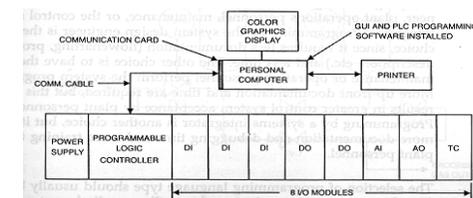
Peripheral Requirements

- ◆ Peripheral = other equipment in the PLC system that is not directly connected to field I/O devices
 - Compact portable programming device from PLC manufacturer
 - Portable PC with PLC software
 - Magnetic tape storage unit to store control program
 - PROM Programmer
 - Process I/O simulators
 - Communications modules
 - 4 Depends on plant network design
 - 4 Extra modules is required for integration within different brands
 - Operator interfaces
 - 4 Hard-wired local and main control panels
 - 4 GUI software runs on a personal computer
 - 4 Intelligent peripheral devices such as touch screen
 - 4 Industrial PC with function keys and GUI software

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System Drawing

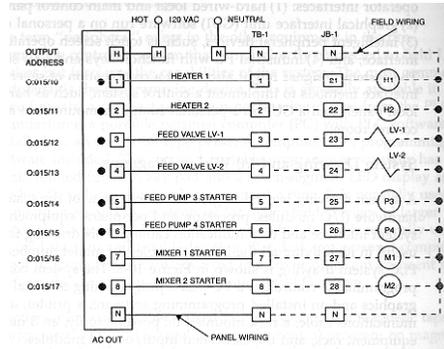
- ◆ Gives an overall view of the system hardware
 - I/O modules
 - processor
 - peripheral equipment
 - system interface
 - communication cabling
- ◆ Useful in identifying all the interface cables by model number



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Example of I/O Wiring Diagrams

- ◆ Field wiring is normally indicated by a dashed line
- ◆ PLC output addresses are given on the left-hand side
- ◆ TB = Terminal Box
- ◆ JB = Junction Box



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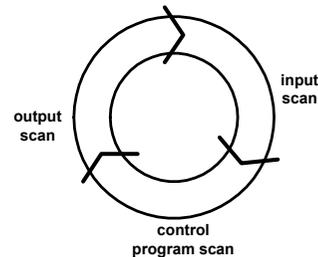
System Programming

- ◆ Person involved in system programming :
 - System design engineer
 - Plant operations personnel
 - Maintenance personnel
 - Control system integrator
- ◆ Programming by system design engineer takes less time and require less documentation (flowcharting, process description, etc.)
- ◆ Selection of programming language type should usually be left to plant operations personnel for easier maintenance and troubleshooting

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Real Time Consideration

- ◆ The period required to examine inputs, perform the control logic, and execute the outputs is called "*scan time*"
- ◆ Scan time must be determined correctly to achieve sufficient real-time performance
- ◆ The numbers of I/O points and complex control algorithms affects scan time



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Installation

- ◆ Control Panel Design
 - Layout
 - Heating Consideration
 - Enclosure Standards (NEMA)
- ◆ Maintenance Features
- ◆ Panel Duct and Wiring Design
- ◆ Power Distribution Design
- ◆ Grounding Considerations
- ◆ Electrical Interference Considerations
- ◆ I/O Module Installation and Wiring
- ◆ Equipment Layout Design

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