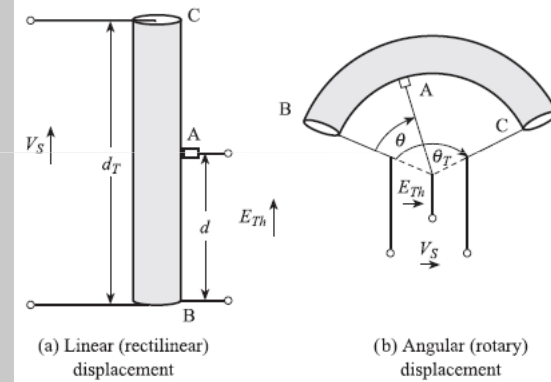


Bab 6. Elemen Pengindera (Sensing Element)

Dr. Yeffry Handoko Putra, M.T

Resistive sensing elements

❖ Potensiometer Displacement Sensor

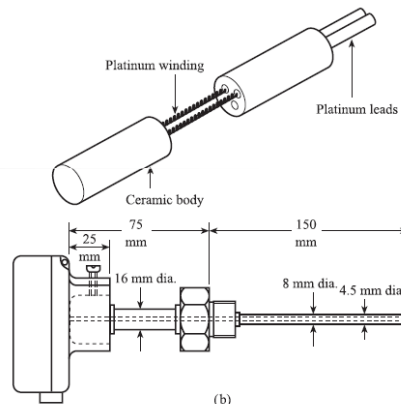
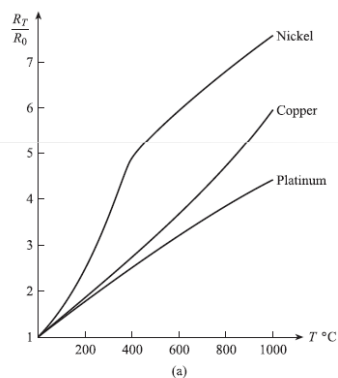


$$E_{Th} = V_S x = V_S d / d_T$$

$$E_{Th} = V_S \theta / \theta_T = V_S x$$

Resistive metal and semiconductor sensors for temperature measurement

$$R_T = R_0(1 + \alpha T + \beta T^2 + \gamma T^3 + \dots)$$



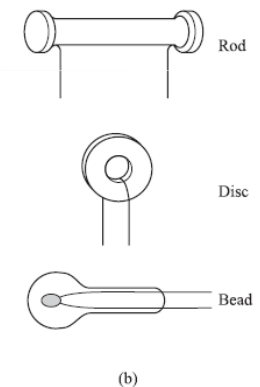
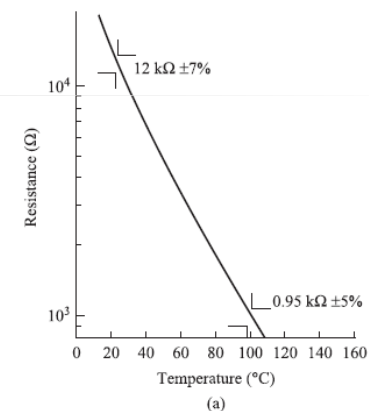
Platinum

$$\text{❖ } R_0 = 100.0 \, \Omega, R_{100} = 138.50 \, \Omega, R_{200} = 175.83 \, \Omega,$$

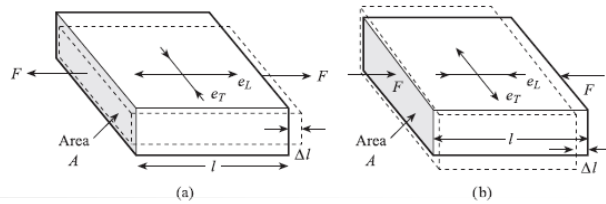
$$\text{❖ } \alpha = 3.91 \times 10^{-3} \, ^\circ\text{C}^{-1} \text{ and } \beta = -5.85 \times 10^{-7} \, ^\circ\text{C}^{-2}.$$

Termistor

$$R_\theta = R_{\theta_1} \exp \beta \left[\frac{1}{\theta} - \frac{1}{\theta_1} \right]$$

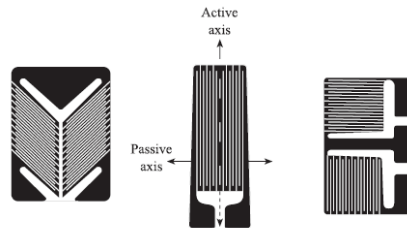


Metal and semiconductor resistive strain gauges (Piezoelectric Effect)



Stress and strain:
(a) Effect of tensile stress
(b) Effect of compressive stress.

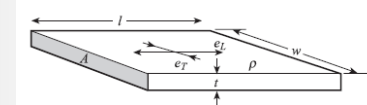
Gauge factor 2.0 to 2.2
Unstrained resistance $120 \pm 1 \Omega$
Linearity within $\pm 0.3\%$
Maximum tensile strain $+2 \times 10^{-2}$
Maximum compressive strain -1×10^{-2}
Maximum operating temperature 150°C .



5

Perhitungan Straingauge

$$\Delta R = \left(\frac{\partial R}{\partial l} \right) \Delta l + \left(\frac{\partial R}{\partial A} \right) \Delta A + \left(\frac{\partial R}{\partial \rho} \right) \Delta \rho$$



Gauge Factor :

$$G = 1 + 2\nu + \frac{1}{e} \frac{\Delta \rho}{\rho}$$

ν = poisson ratio (0,25-0,44)

e = elastisitas

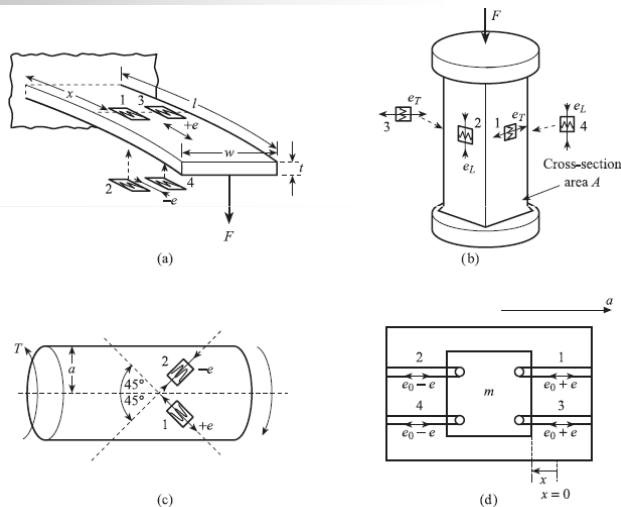
ρ = tahanan dalam

$$\frac{\Delta R}{R_0} = Ge$$

6

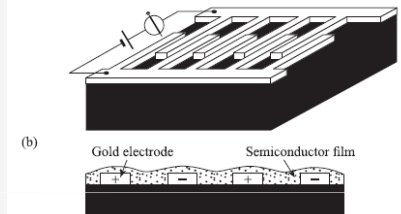
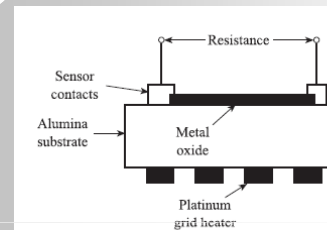
Practical elastic sensing elements using strain gauges

Figure 8.20 Practical elastic sensing elements using strain gauges:
(a) Cantilever load cell
(b) Pillar load cell
(c) Torque sensor
(d) Unbonded strain gauge accelerometer.

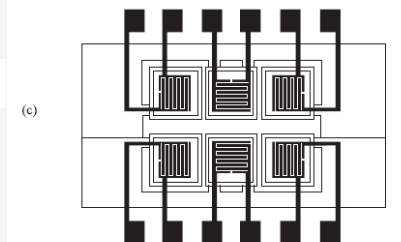
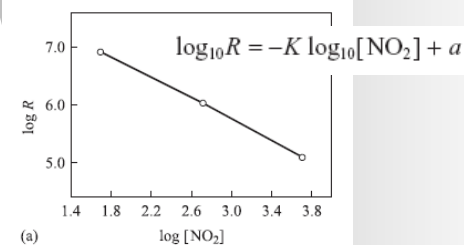


7

Semiconductor resistive gas sensors (HCl, NO₂, H₂S)

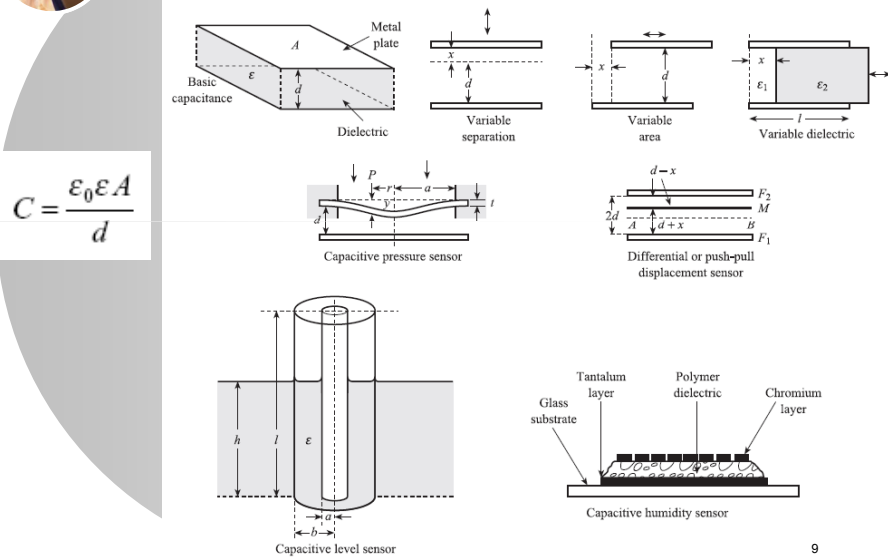


Untuk NO₂



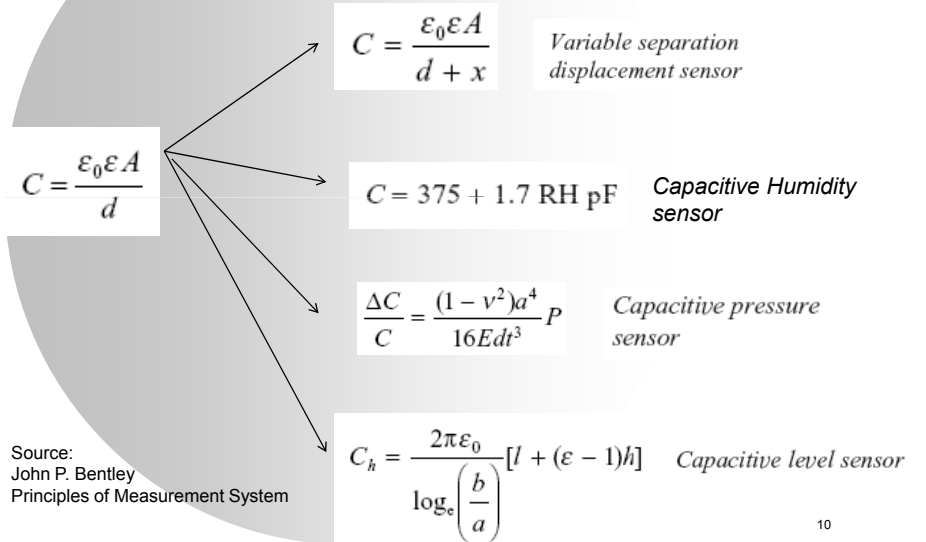
8

Capacitive sensing elements



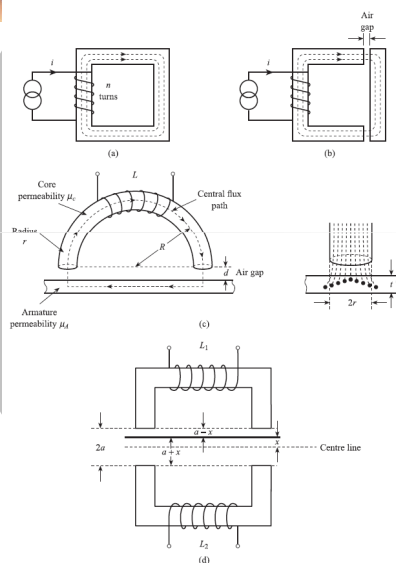
9

Capacitive sensing elements



10

Inductive sensing elements

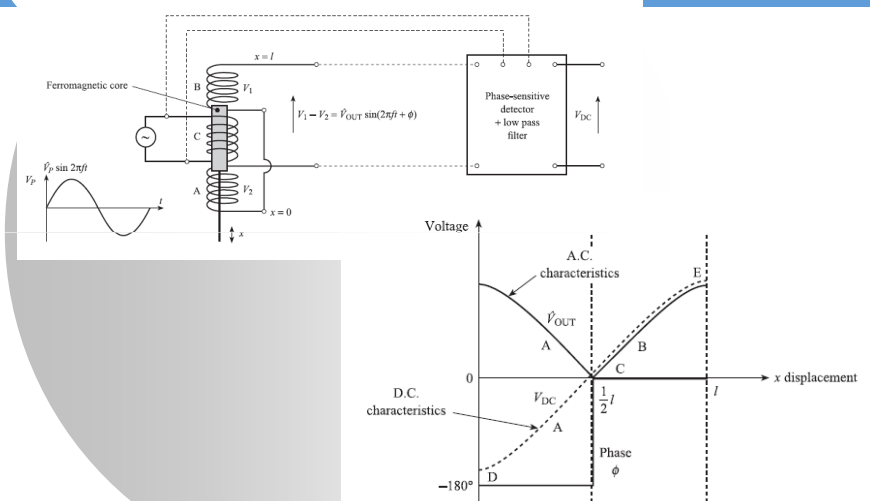


$$L = \frac{N^2}{R}$$

L = Induktansi
N = Total Fluks
i = Arus
n = jumlah lilitan
R = Reluktansi

11

Linear Variable Differential Transformer (LVDT) displacement sensor



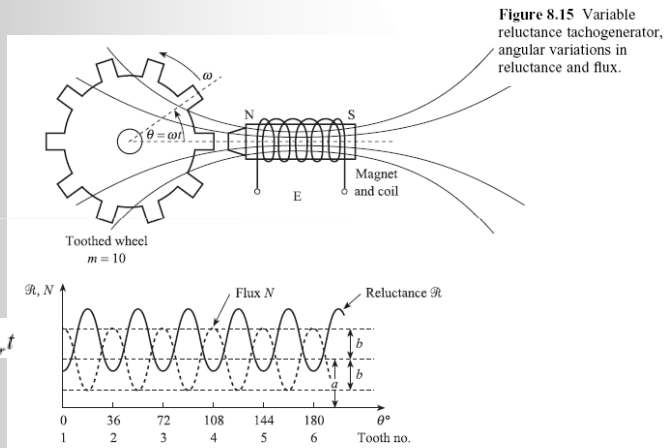
12

Electromagnetic sensing elements

$$E = -\frac{dN}{dt}$$

$$E = b m \omega_r \sin m \omega_r t$$

$m = \text{nomor gigi}$



13

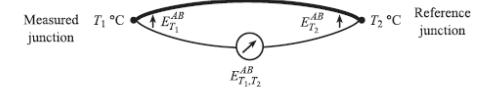
Thermoelectric sensing elements

Figure 8.16
Thermocouple principles.

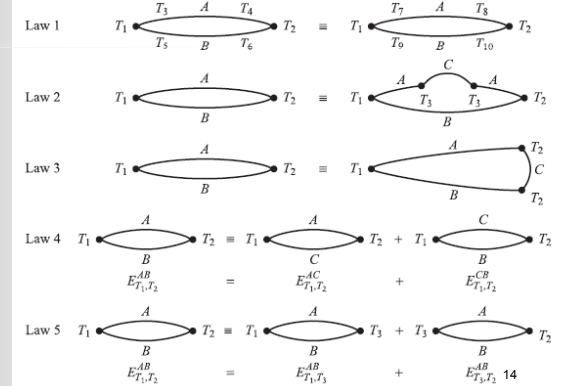
$$E_{T_1, T_2}^{AB} = E_{T_1}^{AB} - E_{T_2}^{AB}$$

$$= a_1(T_1 - T_2) + a_2(T_1^2 - T_2^2) + a_3(T_1^3 - T_2^3) + \dots$$

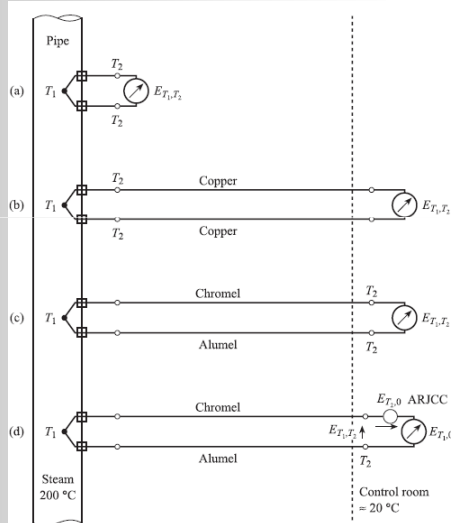
Thermocouple circuit



Thermocouple laws



Termocouple Instalation



15

Elastic sensing elements

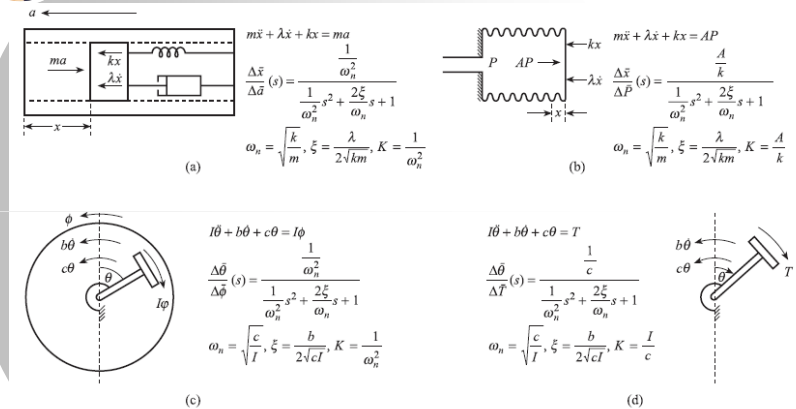
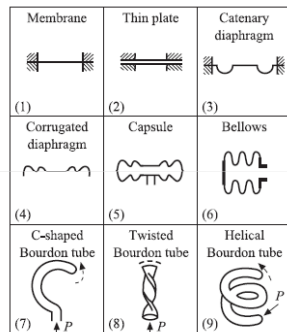
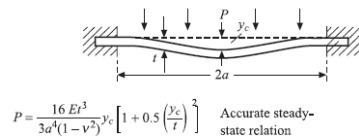


Figure 8.19 Dynamic models of elastic elements:
(a) Linear accelerometer
(b) Pressure sensor
(c) Angular accelerometer
(d) Torque sensor.

16



(a)



$$P = \frac{16 E t^3}{3 a^4 (1 - \nu^2)} y_c \left[1 + 0.5 \left(\frac{y_c}{t} \right)^2 \right] \quad \text{Accurate steady-state relation}$$

if $\left(\frac{y_c}{t} \right) \ll 1$ then

$$\text{Steady-state sensitivity } K = \frac{y_c}{P} = \frac{3 a^4 (1 - \nu^2)}{16 E t^3} = \frac{1}{16 t \gamma}$$

and

$$\text{Natural frequency } f_n = \frac{2.56}{\pi} \sqrt{\frac{E t^2}{3 a^4 (1 - \nu^2) \rho}} = \frac{2.56}{\pi} \sqrt{\frac{\gamma}{\rho}} \text{ Hz}$$

(b)

Figure 8.21 Elastic pressure sensing elements:
(a) Different types (after Neubert^[12])
(b) Flat circular diaphragm.

E = Young's modulus
 ν = Poisson's ratio
 ρ = density
 $\gamma = \frac{E t^2}{3 a^4 (1 - \nu^2)}$

Ion selective electrodes

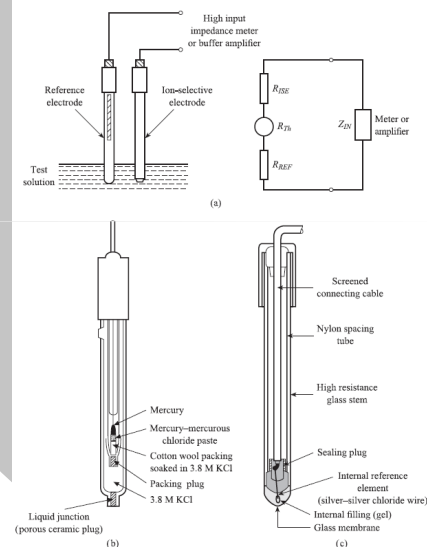


Figure 8.25 Ion-selective electrodes:
(a) Basic system for ion concentration measure and equivalent circuit (after Bailey^[17], © P. L. Bailey 1980. Reprinted by permission of John Wiley & Sons Ltd)
(b) Calomel reference electrode (after Thompson^[18]).