



# Chap 3a. Propagation Characteristic



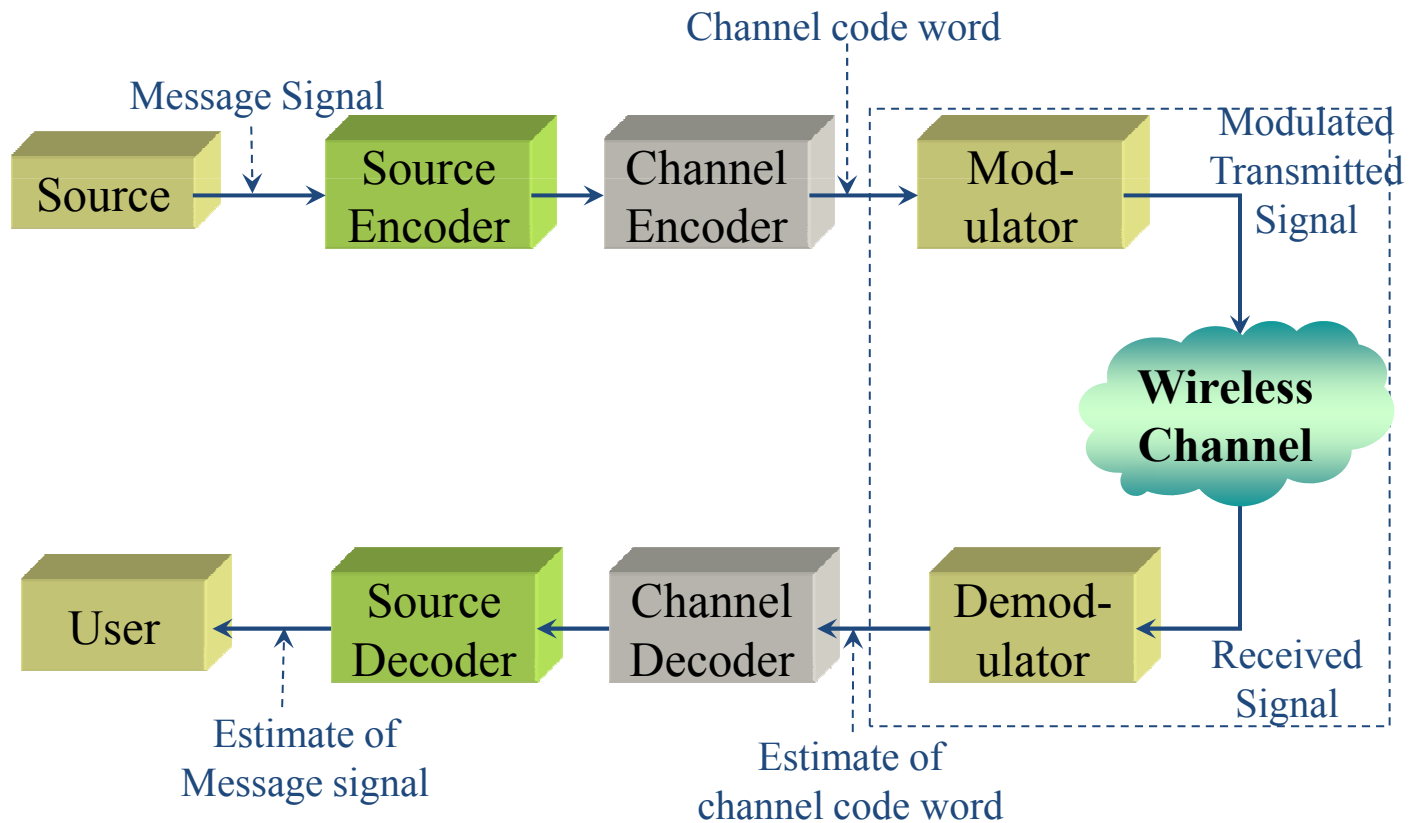
**Dr. Yeffry Handoko Putra, M.T**

Computer Engineering Department  
Universitas Komputer Indonesia

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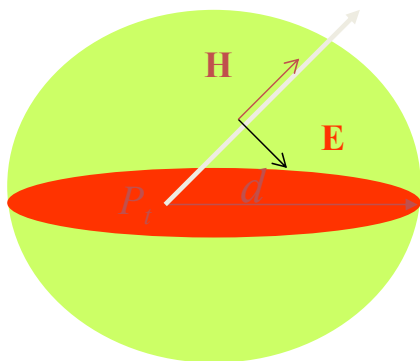
- Radiation from Antenna
- Propagation Model (Channel Models)
  - Free Space Loss
- Plan Earth Propagation Model
- Practical Models
- Summary

# Wireless Communication System

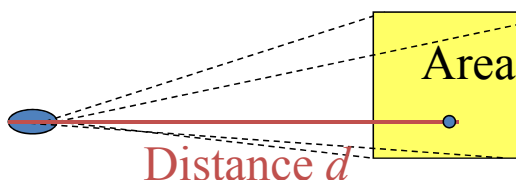
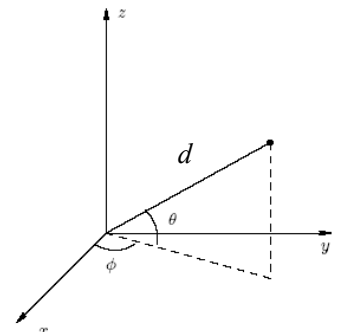


## Antenna - Ideal

- Isotropics antenna: In free space radiates power equally in all direction. Not realizable physically



EM fields around a transmitting antenna, a polar coordinate



- $d$ - distance directly away from the antenna.
- $\phi$  is the azimuth, or angle in the horizontal plane.
- $\theta$  is the zenith, or angle above the horizon.



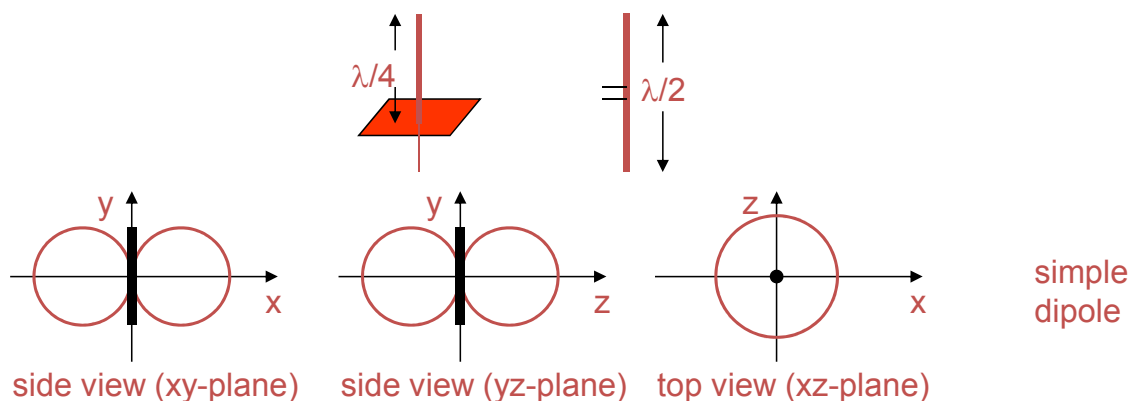
# Antenna - Real

- Not isotropic radiators, but always have directive effects (vertically and/or horizontally)
- A well defined radiation pattern measured around an antenna
- Patterns are visualised by drawing the set of constant-intensity surfaces



## Antenna – Real - Simple Dipoles

- Not isotropic radiators, e.g., dipoles with lengths  $\lambda/4$  on car roofs or  $\lambda/2$  as Hertzian dipole

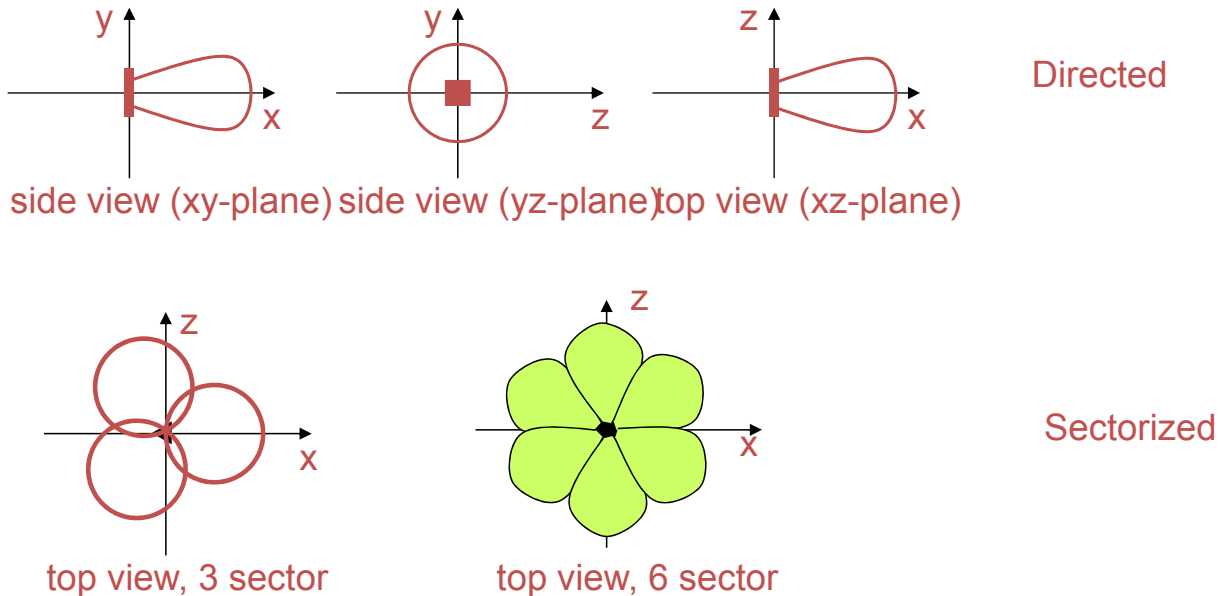


- Example: Radiation pattern of a simple Hertzian dipole  
shape of antenna is proportional to the wavelength



## Antenna – Real - **Directed and Sectorized**

- Used for microwave or base stations for mobile phones (e.g., radio coverage of a valley)



## Antenna - **Ideal** - *contd.*

- The power density of an ideal loss-less antenna at a distance  $d$  away from the transmitting antenna:

$$P_a = \frac{P_t G_t}{4\pi d^2} \quad \text{W/m}^2$$

Note: the area is for a sphere.

- $G_t$  is the transmitting antenna gain
- The product  $P_t G_t$  : **Equivalent Isotropic Radiation Power (EIRP)**

which is the power fed to a perfect isotropic antenna to get the same output power of the practical antenna in hand.



## Antenna - Ideal - contd.

- The strength of the signal is often defined in terms of its Electric Field Intensity  $E$ , because it is easier to measure.

$$P_a = E^2 / R_m \quad \text{where } R_m \text{ is the impedance of the medium. For free space } R_m = 377 \text{ Ohms.}$$

$$E^2 = \frac{P_t R_m}{4\pi d^2} \quad \text{and} \quad E = \sqrt{\frac{P_t R_m}{4\pi d^2}} \quad \text{V/m}$$



## Antenna - Ideal - contd.

- The receiving antenna is characterized by its effective aperture  $A_e$ , which describes how well an antenna can pick up power from an incoming electromagnetic wave
- The effective aperture  $A_e$  is related to the gain  $G_r$  as follows:

$$A_e = P_r / P_a \Rightarrow A_e = G_r \lambda^2 / 4\pi$$

which is the equivalent power absorbing area of the antenna.

$G_r$  is the receiving antenna gain and  $\lambda = c/f$



# Signal Propagation (Channel Models)



## Channel Models

- High degree of variability (in time, space etc.)
- Large signal attenuation
- Non-stationary, unpredictable and random
  - Unlike wired channels it is highly dependent on the environment, time space etc.
- Modelling is done in a statistical fashion
- The location of the base station antenna has a significant effect on channel modelling
- Models are only an approximation of the actual signal propagation in the medium.
- Are used for:
  - performance analysis
  - simulations of mobile systems
  - measurements in a controlled environment, to guarantee repeatability and to avoid the expensive measurements in the field.

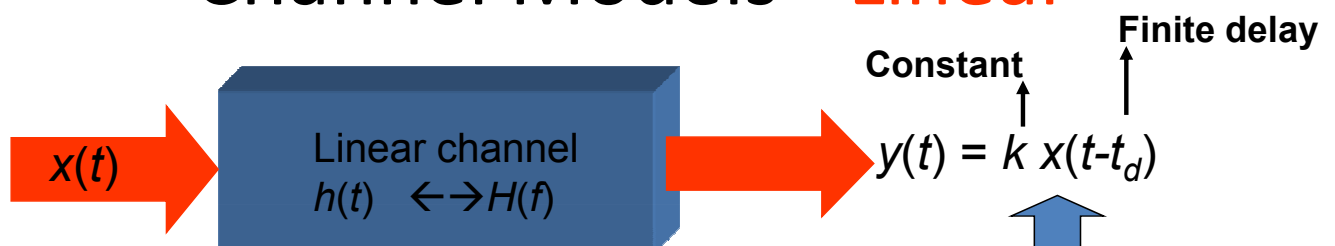


# Channel Models - Classifications

- **System Model - Deterministic**
- **Propagation Model- Deterministic**
  - Predicts the received signal strength at a distance from the transmitter
  - Derived using a combination of theoretical and empirical method.
- **Stochastic Model - Rayleigh channel**
- **Semi-empirical (Practical +Theoretical) Models**



## Channel Models - Linear



- Therefore for a linear channel is:

$$|H(f)| = |k|, \arg H(f) = -2\pi f t_d$$

↑  
Amplitude  
distortion

↑  
Phase  
distortion

$$\begin{aligned}
 y(t) &= k x(t-t_d) \\
 \Updownarrow \\
 H(f) &= F[y(t)] \\
 &= k e^{-j\omega t_d} X(f) \\
 &= H(f) X(f) \\
 \text{where } H(f) &= k e^{-j\omega t_d}
 \end{aligned}$$

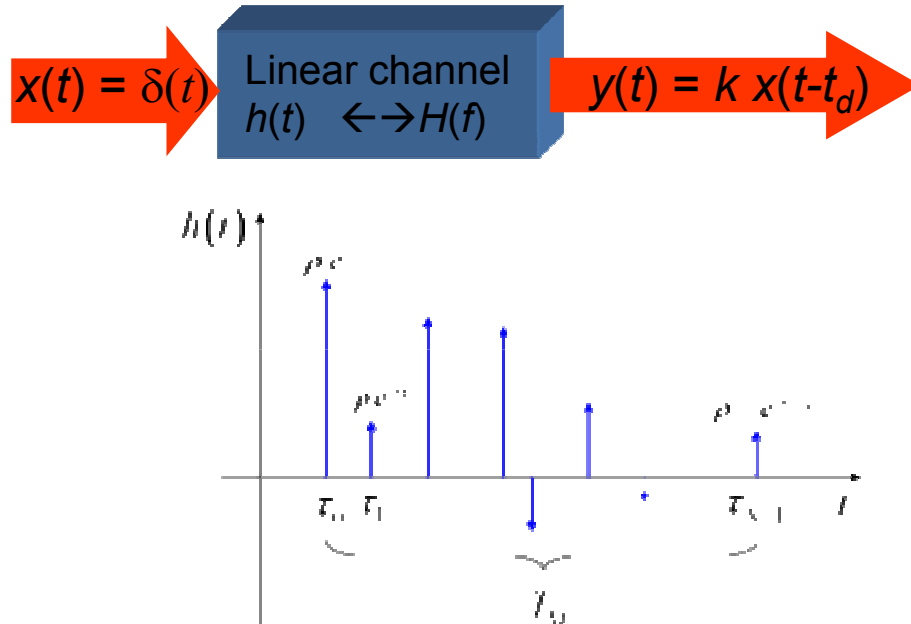
- **The phase delay**  $t_d(f) = -\arg H(f) / 2\pi f$

Describes the phase delayed experienced by each frequency component



# Channel Models – Multipath Link

- The mathematical model of the multipath can be presented using the method of the impulse response used for studying linear systems.



# Channel Models – Multipath Link

- Time variable multi-path channel impulse response

$$h_b(t, \tau) = \sum_{i=0}^{N-1} a_i(t, \tau) \exp[j(2\pi f_c \tau_i(t) + \phi_i(t, \tau))] \delta(\tau - \tau_i(t))$$

Where  $a(t-\tau)$  = attenuated signal

- Time invariant multi-path channel impulse response
  - Each impulse response is the same or has the same statistics, then

$$h(\tau) = \sum_{i=0}^{N-1} a_i e^{-j\theta_i} \delta(\tau - \tau_i)$$

Where  $a_i e^{j\theta_i}$  = complex amplitude (i.e., magnitude and phase) of the generic received pulse.

$\tau$  = propagation delay generic  $i^{th}$  impulse

$N$  = number signal arriving from  $N$  path

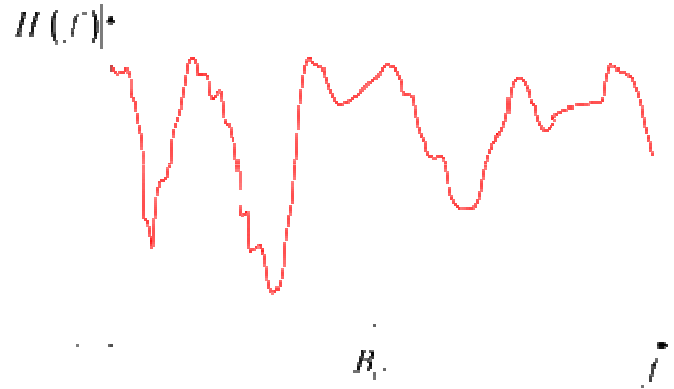
$\delta(.)$  = impulse signal



# Channel Models – Multipath Link

- Channel transfer function

$$H(f) = \int_{-\infty}^{\infty} h(t) e^{-j2\pi ft} dt$$
$$= \sum_{i=0}^{N-1} a_i e^{-j\theta_i} e^{-i2\pi f\tau_i}$$



- Multipath Time

- Mostly used to denote the severity of multipath conditions.
- Defined as the time delay between the 1<sup>st</sup> and the last received impulses.

$$T_{MP} = \tau_{N-1} - \tau_0$$

- Coherence bandwidth - on average the distance between two notches

$$B_c \sim 1/T_{MP}$$



## Propagation Path Loss

- The propagation path loss is

$$L_{PE} = L_a L_{lf} L_{sf}$$

where

$L_a$  is average path loss (attenuation): (1-10 km),

$L_{lf}$  - long term fading (shadowing): 100 m ignoring variations over few wavelengths,

$L_{sf}$  - short term fading (multipath): over fraction of wavelength to few wavelengths.

- Metrics (dBm, mW)

$$[P(\text{dBm}) = 10 * \log[ P(\text{mW}) ]$$



# Propagation Path Loss – Free Space

- Power received at the receiving antenna

$$P_r = P_t G_t G_r \left( \frac{\lambda}{4\pi d} \right)^2$$

Thus the free space propagation path **loss** is defined as:

$$L_f = -10 \log_{10} \frac{P_r}{P_t} = -10 \log_{10} \left[ \frac{G_t G_r \lambda^2}{(4\pi d)^2} \right]$$

- Isotropic antenna has **unity gain ( $G = 1$ )** for both transmitter and receiver.



## Propagation - Free Space—*contd.*

The difference between two received signal powers in free space is:

$$\Delta P = 10 \log_{10} \left( \frac{P_{r1}}{P_{r2}} \right) = 20 \log_{10} \left( \frac{d1}{d2} \right) \quad \text{dB}$$

If  $d_2 = 2d_1$ , the  $\Delta P = -6 \text{ dB}$  i.e 6 dB/octave or 20 dB/decade



# Propagation - Non-Line-of-Sight

- Generally the received power can be expressed as:

$$P_r \propto d^{-\nu}$$

- For line of sight  $\nu = 2$ , and the received power

$$P_r \propto d^{-2}$$

- For non-line of sight with no shadowing, received power at any distance  $d$  can be expressed as:

$$P_r(d) = P_r(1\text{ m}) - 20\log_{10}(d_{\text{ref}}) - 20\nu\log_{10}\left(\frac{d}{d_{\text{ref}}}\right)$$

$$100\text{ m} < d_{\text{ref}} < 1000\text{ m}$$



# Propagation - Non-Line-of-Sight

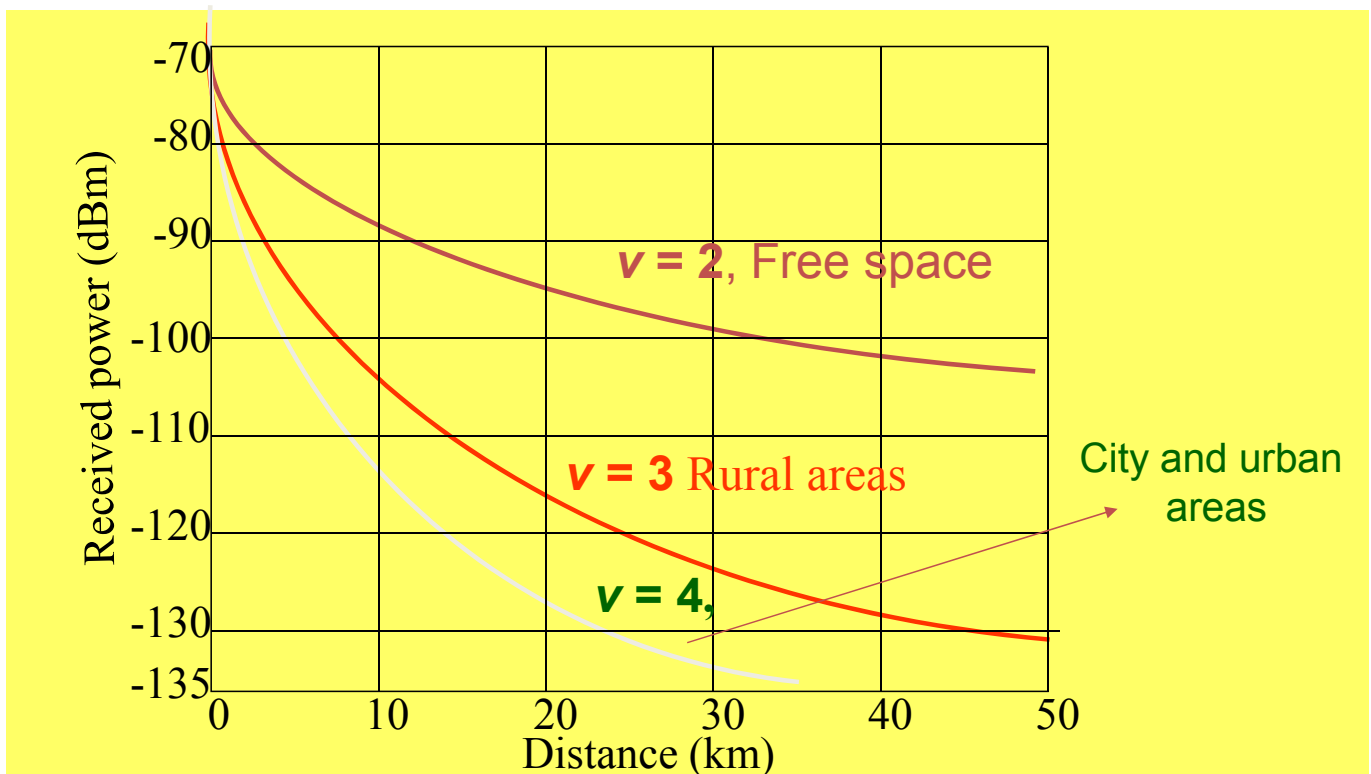
- Log-normal Shadowing

$$P_r(d) = P_r(1\text{ m}) - 10\log_{10}(d_{\text{ref}}) - 20\nu\log_{10}\left(\frac{d}{d_{\text{ref}}}\right) - X_\sigma$$

Where  $X_\sigma$ :  $N(0, \sigma)$  Gaussian distributed random variable



## Received Power for Different Value of Loss Parameter $\nu$



## Propagation Model- Free Space

In terms of frequency  $f$  and the free space velocity of electromagnetic wave  $c = 3 \times 10^8$  m/s it is:

$$L_f = -20 \log_{10} \left( \frac{c/f}{4\pi d} \right) \text{ dB}$$

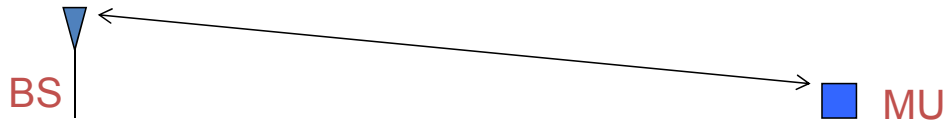
Expressing frequency in MHz and distance  $d$  in km:

$$\begin{aligned} L_f &= -20 \log_{10}(c/4\pi) + 20 \log_{10}(f) + 20 \log_{10}(d) \\ &= -20 \log_{10}(0.3/4\pi) + 20 \log_{10}(f) + 20 \log_{10}(d) \text{ dB} \end{aligned}$$

$$L_f = 32.44 + 20 \log_{10}(f) + 20 \log_{10}(d) \text{ dB}$$



## Propagation Model- Free Space (non-ideal, path loss)



- Non-isotropic antenna gain  $\neq$  unity, and there are additional losses  $L_{ad}$ , thus the power received is:

$$P_r = G_t G_r \frac{P_t \lambda^2}{(4\pi d)^2} \cdot \frac{1}{L_{ad}} \quad d > 0 \text{ and } L \geq 0$$

Thus for **Non-isotropic antenna** the path loss is:

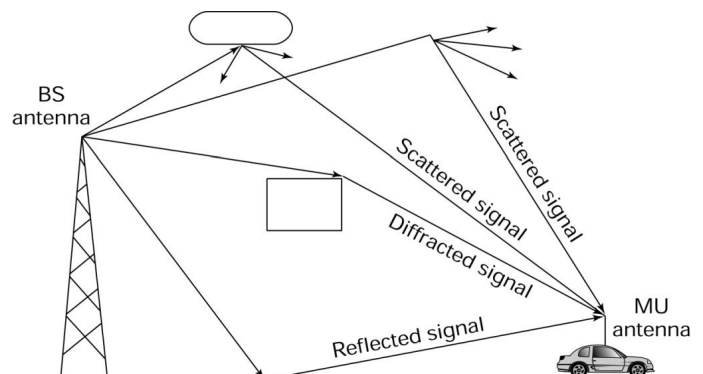
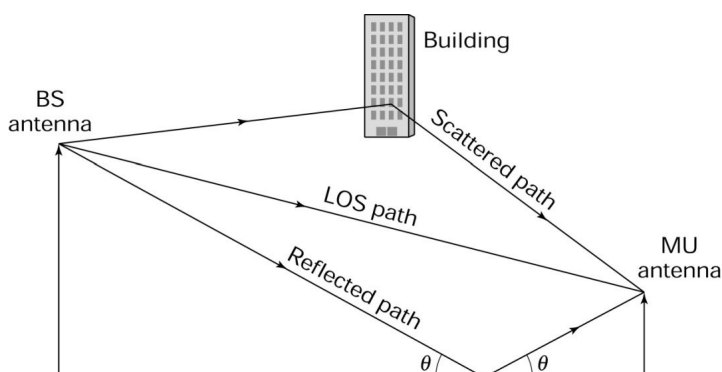
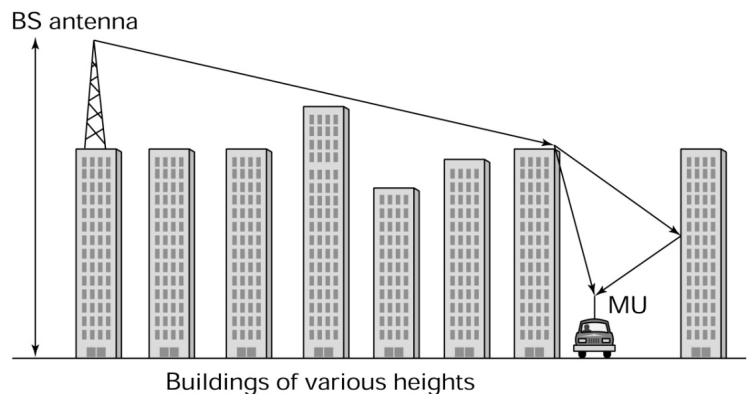
$$L_{f-ni} = -10 \log_{10}(G_t) - 10 \log_{10}(G_r) - 20 \log_{10}(c/4\pi) \\ + 20 \log_{10}(f) + 20 \log_{10}(d) + 10 \log_{10}(L_{ad}) \text{ dB}$$

Note: Interference margin can also be added



## Propagation Model - Mechanisms

- Reflection
- Diffraction
- Scattering

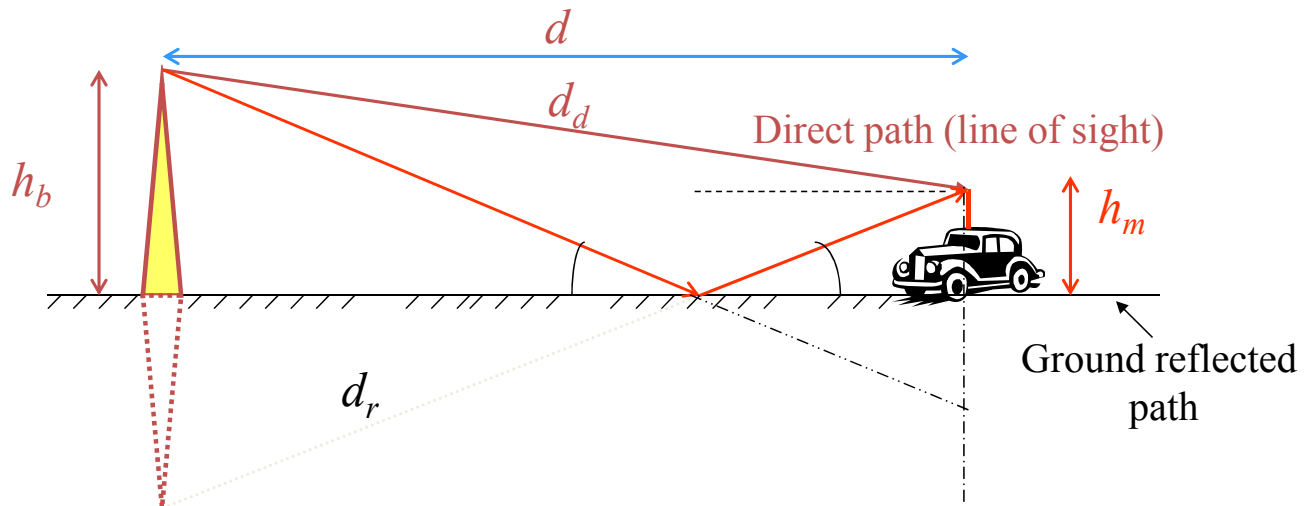


Source: P M Shankar



## Channel Model- Plan Earth Path Loss - 2 Ray Reflection

- In mobile radio systems the height of both antennas (Tx. and Rx.)  $\ll d$  (distance of separation)



From the geometry  $d_d = \sqrt{[d^2 + (h_b - h_m)^2]}$



## Channel Model- Plan Earth Path Loss - *contd.*

Using the binomial expansion

Note  $d \gg h_b$  or  $h_m$ .

$$d_d \cong d \left\{ 1 + 0.5 \left( \frac{h_b - h_m}{d} \right)^2 \right\}$$

Similarly

$$d_r \cong d \left\{ 1 + 0.5 \left( \frac{h_b + h_m}{d} \right)^2 \right\}$$

The path difference

$$\Delta d = d_r - d_d = 2(h_b h_m)/d$$

The phase difference

$$\Delta\phi = \frac{2\pi}{\lambda} \times \frac{2h_b h_m}{d} = \frac{4\pi h_b h_m}{\lambda d}$$



# Channel Model- Plan Earth Path Loss—

*contd.*

## Total received power

$$P_r = P_t G_t G_r \left( \frac{\lambda}{4\pi d} \right)^2 \times |1 + \rho e^{j\Delta\phi}|^2$$

Where  $\rho$  is the reflection coefficient.

For  $\rho = -1$  (low angle of incident) and .

$$1 - e^{-j\Delta\phi} = 1 - \cos \Delta\phi + j \sin \Delta\phi$$

$$\begin{aligned} \text{Hence } |1 - e^{-j\Delta\phi}|^2 &= (1 - \cos \Delta\phi)^2 + \sin^2 \Delta\phi = 2(1 - \cos \Delta\phi) \\ &= 4 \sin^2 (\Delta\phi / 2) \end{aligned}$$



# Channel Model- Plan Earth Path Loss—

*contd.*

Therefore:

$$P_r = P_t G_t G_r \left( \frac{\lambda}{4\pi d} \right)^2 \times 4 \sin^2 \left( \frac{2\pi h_b h_m}{\lambda d} \right)$$

Assuming that  $d \gg h_m$  or  $h_b$ , then  $\left( \frac{2\pi h_b h_m}{\lambda d} \right) \ll 1$   
 $\sin x = x$  for small  $x$

Thus

$$P_r = P_t G_t G_r \left( \frac{h_b h_m}{d^2} \right)^2$$

which is 4<sup>th</sup> power law



## Channel Model- Plan Earth Path Loss— contd.

Propagation path  
loss (mean loss)

$$L_{PE} = -10 \log \left( \frac{P_r}{P_t} \right) = 10 \log \left[ G_t G_r \left( \frac{h_b h_m}{d^2} \right)^2 \right]$$

Compared with the free space =  $P_r = 1/d^2$

In a more general form (*no fading due to multipath*),  
path attenuation is

$$L_{PE} = -10 \log_{10} G_t - 10 \log_{10} G_r - 20 \log_{10} h_b - 20 \log_{10} h_m + 40 \log_{10} d \quad \text{dB}$$

- $L_{PE}$  increases by 40 dB each time  $d$  increases by 10



## Channel Model- Plan Earth Path Loss— contd.

- Including impedance mismatch, misalignment of antennas, pointing and polarization, and absorption The power ratio is:

$$\frac{P_r}{P_t} = G_t(\theta_t, \phi_t) G_r(\theta_r, \phi_r) \left( \frac{\lambda}{4\pi d} \right)^2 (1 + |\Gamma_t|^2) (1 - |\Gamma_r|^2) \left| \overline{a_t} \cdot \overline{a_r}^* \right|^2 e^{-\alpha d}$$

where

$G_t(\theta_t, \phi_t)$  = gain of the transmit antenna in the direction  $(\theta_r, \phi_r)$  of receive antenna.

$G_r(\theta_r, \phi_r)$  = gain of the receive antenna in the direction  $(\theta_r, \phi_r)$  of transmit antenna.

$\Gamma_t$  and  $\Gamma_r$  = reflection coefficients of the transmit and receive antennas

$\mathbf{a}_t$  and  $\mathbf{a}_r$  = polarization vectors of the transmit and receive antennas

$\alpha$  is the absorption coefficient of the intervening medium.



# LOS Channel Model - Problems

- Simple theoretical models do not take into account many practical factors:
  - Rough terrain
  - Buildings
  - Refection
  - Moving vehicle
  - Shadowing

Thus resulting in bad accuracy

## Solution: Semi- empirical Model



## Semi-empirical Model

Practical models are based on combination of measurement and theory. Correction factors are introduced to account for:

- Terrain profile
- Antenna heights
- Building profiles
- Road shape/orientation
- Lakes, etc.

- |  |   |         |
|--|---|---------|
| <ul style="list-style-type: none"><li>• Okumura model</li><li>• Hata model</li></ul> | } | Outdoor |
| <ul style="list-style-type: none"><li>• Saleh model</li><li>• SIRCIM model</li></ul> | } | Indoor  |



# Okumura Model

- Widely used empirical model (no analytical basis!) in macrocellular environment
- Predicts average (median) path loss
- “Accurate” within 10-14 dB in urban and suburban areas
- Frequency range: 150-1500 MHz
- Distance:  $> 1$  km
- BS antenna height:  $> 30$  m.
- MU antenna height: up to 3m.
- Correction factors are then added.



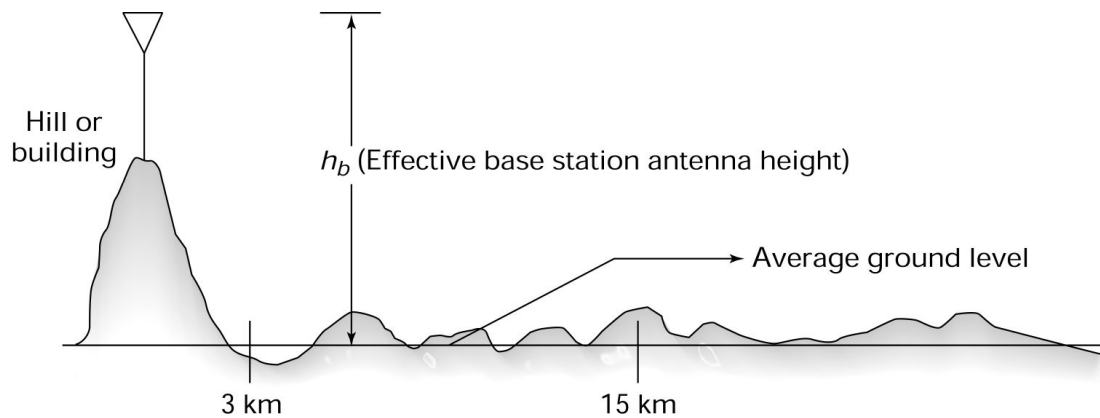
## Hata Model

- Consolidate Okumura's model in standard formulas for **macrocells** in urban, suburban and open rural areas.
- Empirically derived correction factors are incorporated into the standard formula to account for:
  - Terrain profile
  - Antenna heights
  - Building profiles
  - Street shape/orientation
  - Lakes
  - Etc.



# Hata Model – *contd.*

- The loss is given in terms of effective heights.
- The starting point is an urban area. The BS antennae is mounted on tall buildings. The effective height is then estimated at 3 - 15 km from the base of the antennae.



## Hata Model - Limits

- Frequency range: 150 - 1500 MHz
- Distance: 1 – 20 km
- BS antenna height: 30- 200 m
- MU antenna height: 1 – 10 m

# Hata Model – Standard Formula for Average Path Loss for Urban Areas

$$L_{pl-u} = 69.55 + 26.16 \log_{10}(f) + (44.9 - 6.55 \log_{10} h_b) \log_{10} d - 13.82 \log_{10} h_b - a(h_{mu}) \quad (\text{dB})$$

## Correction Factors are:

- Large cities

$$a(h_{mu}) = 8.3 [\log_{10}(1.5 h_{mu})]^2 - 1.1 \quad (f \leq 200 \text{ MHz}) \quad \text{dB}$$

$$a(h_{mu}) = 3.2 [\log_{10}(11.75 h_{mu})]^2 - 4.97 \quad (f \geq 400 \text{ MHz}) \quad \text{dB}$$

- Average and small cities

$$a(h_{mu}) = [1.1 \log_{10}(f) - 0.7] h_{mu} - [1.56 \log_{10}(f) - 0.8] \quad \text{dB}$$



## Hata Model – Average Path Loss for Urban Areas *contd.*

### Carrier frequency

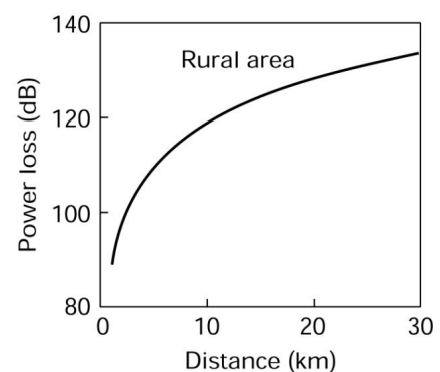
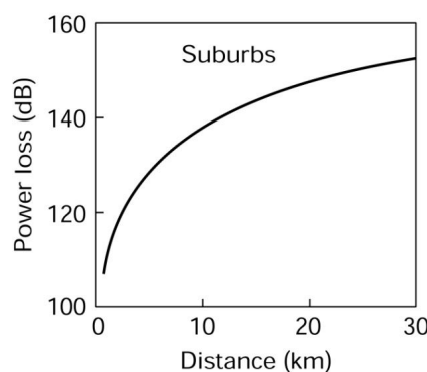
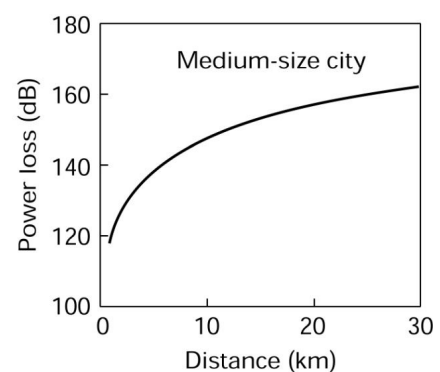
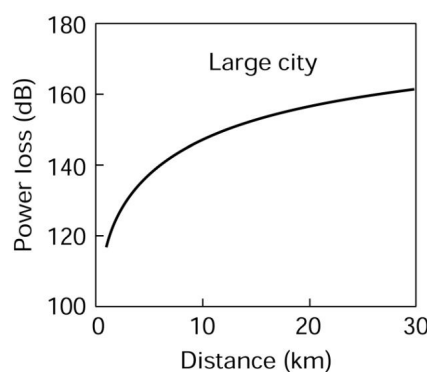
- 900 MHz,

### BS antenna height

- 150 m,

### MU antenna height

- 1.5m.



# Hata Model – Average Path Loss for Suburban and Open Areas

- Suburban Areas

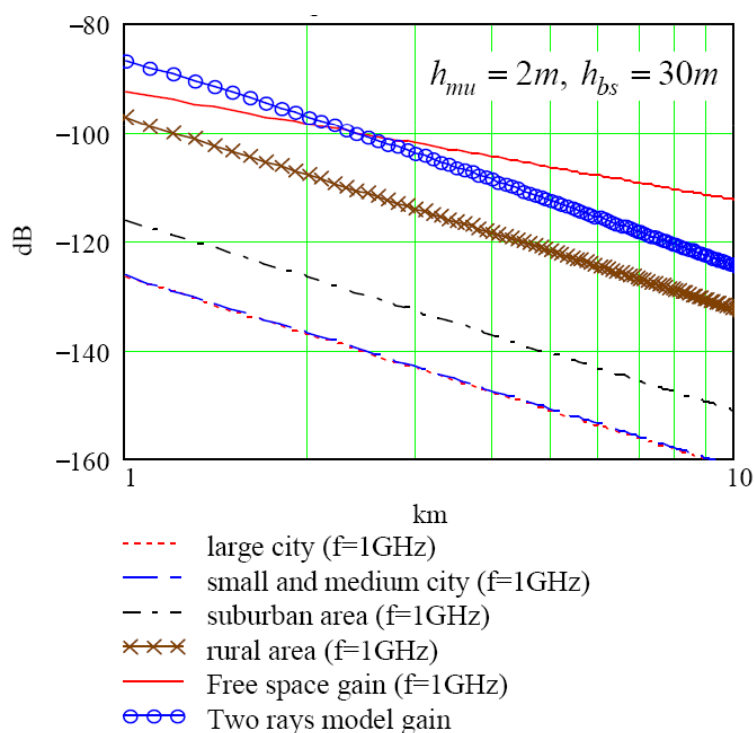
$$L_{pl-su} = L_{pl-u} - 2 \left[ \text{Log}_{10} \left( \frac{f}{28} \right) \right]^2 - 5.4$$

- Open Areas

$$L_{pl-o} = L_{pl-u} - 4.78(\text{Log}_{10} f)^2 - 18.33 \text{Log} f - 40.94$$



## Hata Model - Average Path Loss



# Improved Model

- Hata-Okumura model are not suitable for lower BS antenna heights (2 m), and hilly or moderate-to-heavy wooded terrain.
- To correct for these limitations the following model is used [1]:
- For a given close-in distance  $d_{ref}$  the average path loss is:

$$L_{pl} = A + 10 \nu \log_{10} (d / d_{ref}) + s \quad \text{for } d > d_{ref} \quad (\text{dB})$$

where

$$A = 20 \log_{10}(4 \pi d_{ref} / \lambda)$$

$\nu$  is the path-loss exponent =  $(a - b \text{ hb} + c / \text{hb})$

hb is the height of the BS: between 10 m and 80 m

$d_{ref} = 100\text{m}$  and

a, b, c are constants dependent on the terrain category

s is representing the shadowing effect



# Improved Model

Model parameter	Terrains		
	Type A	Type B	Type C
a	4.6	4	3.6
b	0.0075	0.0065	0.005
c	12.6	17.1	20

The typical value of the standard deviation for **s** is between 8.2 And 10.6 dB, depending on the terrain/tree density type

- Terrain A: The maximum path loss category is hilly terrain with moderate-to-heavy tree densities .
- Terrain B: Intermediate path loss condition
- Terrain B: The minimum path loss category which is mostly flat terrain with light tree densities



# Summary

- Attenuation is a result of reflection, scattering, diffraction and reflection of the signal by natural and human-made structures
- The received power is inversely proportional to  $(\text{distance})^v$ , where  $v$  is the loss parameter.
- Studied channel models and their limitations

